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Parameter and Optimal Performance Modelling in Smart Buildings

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Motivation

Smart buildings can effectively reduce CO2 energy consumption emissions and while human comfort through energy increasing management, sensing, control, and information technologies.

2012 Main Objectives

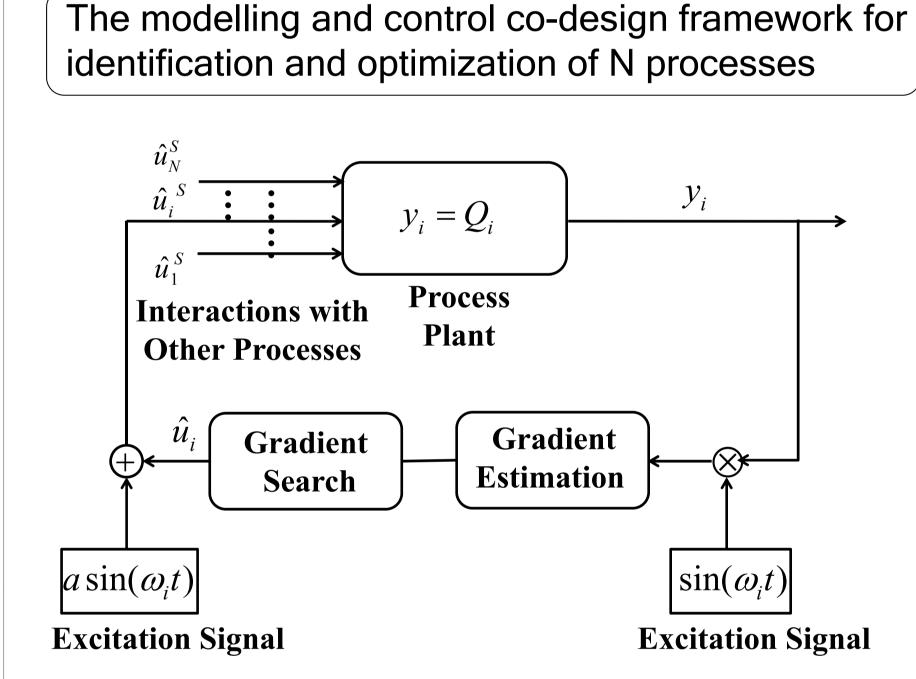
- Design a scheme to model the parameters and optimal performance for the physical and cyber processes of smart buildings. This scheme will ultimately consider:

The Problem and Approach

- How to characterize the interactions among networked physical processes in the building?
- How to handle the uncertainties that cannot be modeled?

- It is challenging to model the complex physical and cyber processes (e.g., HVAC, lighting, occupant activities) in smart buildings, especially as an integrated system.
- It is highly demanded to characterize and model the optimal performance of processes in smart buildings so as to predict and optimize the energy consumption and human comfort.
- The optimal performance of the processes in smart buildings may not be invariant due to uncertainties, faults, occupant activities, and varying environment conditions.

Identification and Optimization Scheme



- Continuous physical processes
- Discrete-time events, faults, cyber processes
- Occupant behavior
- Disturbances and uncertainties
- Interdependencies among the processes and events.
- Develop modelling tools for smart buildings by adapting multi-agent theory, games, and machine learning tools.
- Develop a unified framework for identification and optimization of physical processes subject to uncertainties and networked interactions.

N-Process Games

Design action strategies for N processes to converge to a small neighborhood of a Nash equilibrium (NE)

 $Q_i(u_i^*(t), u_{-i}^*(t), \varsigma_i(t)) > Q_i(u_i(t), u_{-i}^*(t), \varsigma_i(t))$ $\forall u_i \neq u_i^*, i \in \mathbb{N}$ Time-Varying NE $Q_i^*(t) \triangleq Q_i(u_i^*(t), u_{-i}^*(t), \varsigma_i(t))$

- How to design a scheme to identify the optimal performance and certain parameters in the model?
- How to balance the trade-off between accuracy and convergence speed?

Proposed approach:

• A multi-agent method is adapted to describe the processes. Each process is modeled as an agent. Games are formulated to handle the interactions among the processes. An extremum learning method is designed to estimate the parameters and optimal performance of the processes.

Gradient Estimation

Real-time gradient estimation: Design an update law to extract the gradient of the utility function under uncertainties and networked interactions.

$$\mu(u_i, \hat{u}_{-i}^S, \varsigma_i) = \frac{1 - e^{-Ts}}{Ts} \left[Q_i(u_i, \hat{u}_{-i}^S, \varsigma_i) \sin(\omega_i t) \right]$$

 $\mu(u_i, \hat{u}_{-i}^S, \varsigma_i) = \frac{\alpha}{2} Q_{iu_i}(\hat{u}_i, \hat{u}_{-i}^S, \varsigma_i(t)) + \mathcal{O}(\cdot)$ Example: For a single process with utility function $Q(u,\varsigma) = 4\varsigma^3 - \varsigma(u^2 - \varsigma)^2$, ς uncertain parameter

Gradient Search

Gradient Search for Tracking a Time-Varying Nash equilibrium: Consider an update law for \hat{u}_i of the form $\hat{u}_i = \lambda_i$. Design a gradient search law $\lambda_i(t)$ such that $\|\hat{u}_i(t) - u_i^*(t)\| \to 0$ as $t \to \infty, i \in \mathbb{N}$ using the estimated signals $\hat{u}_i(t)$ and $Q_{iu_i}(\hat{u}_i, \hat{u}_{-i}, \varsigma_i)$ where $\hat{u}_i(t)$ is the estimation of $u_i(t)$ and $Q_{iu_i}(\hat{u}_i, \hat{u}_{-i}, \varsigma_i)$ is the estimated gradient of $Q_i(u_i, u_{-i}, \varsigma_i)$ with respect to $u_i(t)$ at $u_i(t) = \hat{u}_i(t)$.

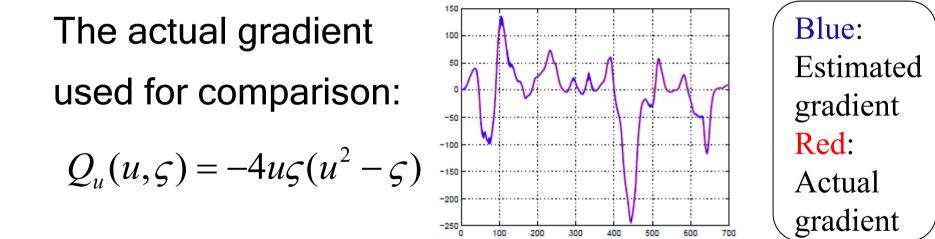
In classic extremum seeking scheme for a constant extremum, steepest descent can be used. For the case of time-varying Nash equilibrium, a new method is needed.

Gradient $\lambda_i = k_1 Q_{iu_i} + \Phi - c_1 \hat{u}_i$ Search $\dot{\Phi} = c_2 k_1 Q_{iu_i} + k_2 sgn(Q_{iu_i})$ Algorithm

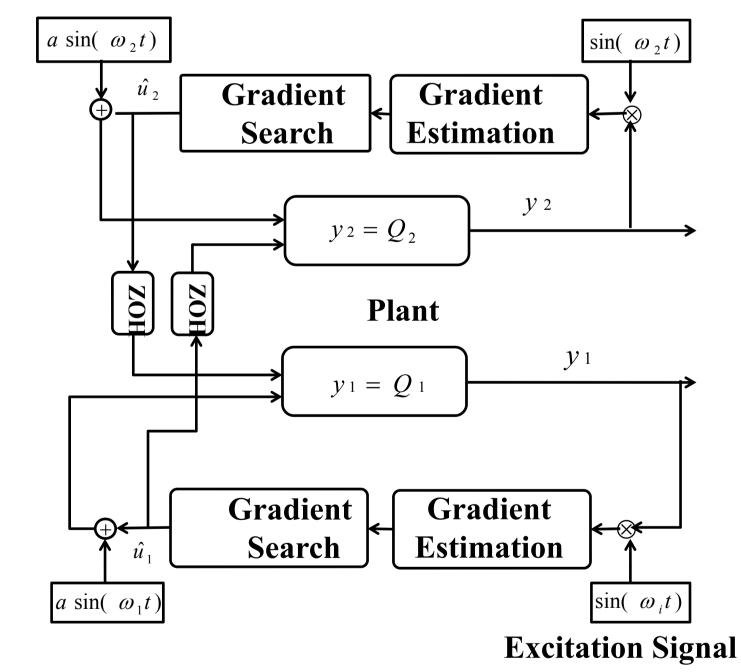
The convergence can be enabled by designing the gradient estimation and gradient search modules and well selection of the excitation signals.

Gradient Search Example

Consider the time-dependent mapping $Q = (3 + \sin(t))[3 - (\theta + 1 - 4\sin(t))^2]$ The extremum point and the optimal value are $\theta^*(t) = 4\sin(t) - 1,$ $Q^*(t) = 3(3 + \sin(t)).$ The gradient is $Q_{\theta} = -2(3 + 2\sin(t))(\bar{\theta} + 1 - \sin(t))$ Blue: Maximum Red: Generated 10 Time [sec] 10 Time [sec] **Proposed method Steepest descent**



Block Diagram for An Example with **Two Processes**



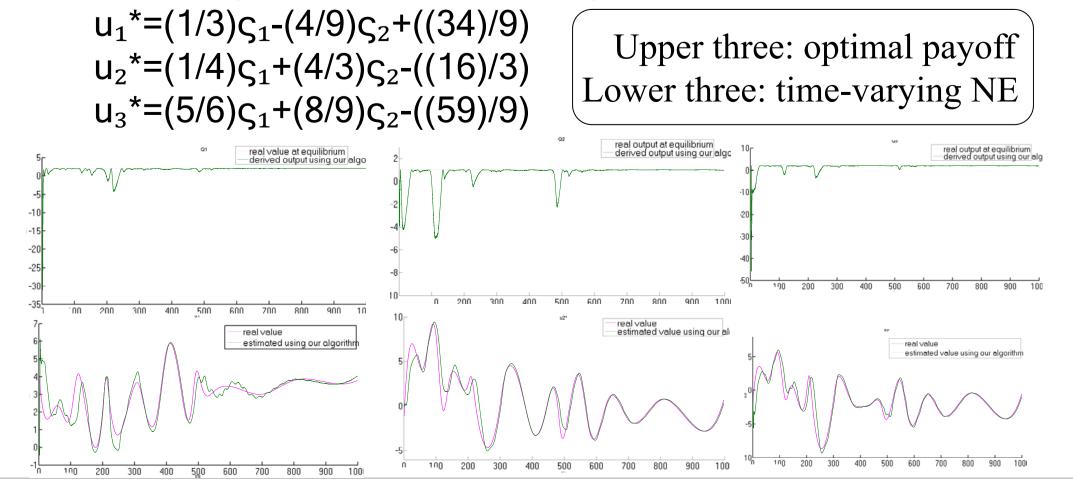
Simulation for Three Processes Consider a three-process game with the payoff functions

Conclusions

Future Goals

 $Q_1 = -(u_1 - (1/3)u_2 + u_3 - \varsigma_1 - 1)^2 + 2$ ς_1, ς_2 are uncertainties $Q_2 = -(-(1/4)u_1 + u_2 - (1/2)u_3 - \varsigma_2 + 3)^2 + 1$ $Q_3 = -(-u_1 - u_2 + u_3 + 5)^2 + 2$

The Nash equilibrium for the three processes are:



Proposed a modelling method by leveraging multi-agent theory, games, and learning methods.

- Developed a unified framework for identification and optimization of physical processes subject to uncertainties and networked interactions.
- Designed estimation algorithms to extract measurable information from the processes.
- Designed a distributed seeking method to learn the process parameters and optimal performance.
- Study processes that have different dimensions and dynamic properties
- Consider both discrete-time and continuoustime processes within the same framework
- Explore event-driven mechanisms to integrate occupant behaviors into the identification and optimization scheme
- Conduct experimental test in a building to evaluate the proposed scheme and methods

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